Lecture 1: Introduction to quantum computing, qubits, gates and superposition

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- What is quantum computing?
- Why do we need it?
- How can we make it work for the problems we want to solve?

 What is quantum computing? A type of computing where the programming model follows principles of quantum mechanics • What is quantum computing?

A type of computing where the programming model follows principles of quantum mechanics Nielsen, Chuang, Ch. 2

Postulate 1: Associated to any isolated physical system is a complex vector space with inner product (that is, a Hilbert space) known as the *state space* of the system. The system is completely described by its *state vector*, which is a unit vector in the system's state space.

Introduction

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with syste vector $|\psi'\rangle$ of the system at time t_1 is related to the state $|\psi'\rangle$ of the system at time t_2 by a unitary operator U which depends only on the times t_1 and t_2 ,

$$|\psi'\rangle = U|\psi\rangle.$$
(2.84)

Introduction

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with **Postulate 2**: The evolution of a *closed* quantum system is described by a *unitary*

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Postulate 3: Quantum measurements are described by a collection $\{M_m\}$ of *measurement operators*. These are operators acting on the state space of the system being measured. The index m refers to the measurement outcomes that may occur in the experiment. If the state of the quantum system is $|\psi\rangle$ immediately before the measurement then the probability that result m occurs is given by

$$p(m) = \langle \psi | M_m^{\dagger} M_m | \psi \rangle , \qquad (2.92)$$

and the state of the system after the measurement is

$$\frac{M_m |\psi\rangle}{\sqrt{\langle \psi | M_m^{\dagger} M_m |\psi\rangle}} \,. \tag{2.93}$$

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Postulate 4: The state space of a composite physical system is the tensor product of the state spaces of the component physical systems. Moreover, if we have systems numbered 1 through n, and system number i is prepared in the state $|\psi_i\rangle$, then the joint state of the total system is $|\psi_1\rangle \otimes |\psi_2\rangle \otimes \cdots \otimes |\psi_n\rangle$.

 $\langle \psi | M_m^\dagger M_m | \psi \rangle$

(2.92)

(2.93)

Classical computing

Typical problems we deal with:

- Combinatorial problems
- Evaluation of functions
- Root finding
- Numerical differentiation and integration
- Solving ODEs and PDEs
- Optimization
- Linear algebra (linear systems, eigenproblems)
- Stochastic (Monte Carlo) sampling

Why has classical computing been successfully applied to so many problems?

- Hardware improvements in 20th century
- Hundreds or even thousands of years of algorithm development
- Runge-Kutta method for ODEs early 20th century
- Gauss elimination 19th century (ideas around -3rd century!)
- Euler method for ODEs 18th century
- Stochastic "integration" (Buffon's needle) 18th century
- Newton-Raphson method 17th century (ideas around 1st century!)

$$x = \sqrt{a} \Rightarrow x^2 - a = 0 \Rightarrow x_0 = a, \quad x_{n+1} = (x_n + a/x_n)/2$$

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```
1 #include <stdio.h>
   #include <math.h>
2
3
   int main() {
4
   // parameters
5
     int depth = 100; float a = 2., eps = 1e-4;
6
     // storage
7
     int i; float x, xp;
8
9
     // initialization
10
     x = a; i = 0;
11
12
     // evolution
13
     do {
14
       xp = x; x = (x + a/x) / 2;
15
     i++;
16
     } while( fabs( x-xp ) > eps && i < depth );</pre>
17
18
     // read-out
19
     printf( "sqrt(%g) ~ %g\n", a, x );
20
21
     return 0;
22
23 }
```

```
1 #include <stdio.h>
   #include <math.h>
2
3
   int main() {
4
   // parameters
5
     int depth = 4; float a = 2.;
6
     // storage
7
     int i; float x;
8
9
     // initialization
10
     x = a; i = 0;
11
12
     // evolution
13
14
     do {
       x = (x + a/x) / 2;
15
     i++;
16
     } while( i < depth );</pre>
17
18
     // read-out
19
     printf( "sqrt(%g) ~ %g\n", a, x );
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     return 0;
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```
1 #include <stdio.h>
2 #include <math.h>
3
   int main() {
4
5 // parameters
  float a = 2.;
6
    // storage
7
    float x;
8
9
    // initialization
10
11
     x = a;
12
    // evolution
13
14 x = (x + a/x) / 2;
15 x = (x + a/x) / 2;
    x = (x + a/x) / 2;
16
     x = (x + a/x) / 2;
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    // read-out
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```





• Why do we need quantum computing?

- There are known examples such as factorization into primes, traveling salesman and other problems that require non-polynomial computational effort
- As a physics example, consider *classical* Ising model:

$$E(\{s\}) = -J \sum_{\langle ij \rangle} s_i s_j, \quad s_i \in \{-1, 1\}$$
$$Z = \sum_{\{s\}} \exp\left(-\frac{E(\{s\})}{k_B T}\right)$$

• The average energy at a given temperature *T*:

$$\langle E \rangle(T) = \frac{1}{Z} \sum_{\{s\}} E(\{s\}) \exp\left(-\frac{E(\{s\})}{k_B T}\right)$$

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Scaling

- To calculate (*E*) on a N³ lattice requires summing over 2^{N³} spin configurations
- Assume that N = 10 (a very modest lattice) and it takes *n* floating point operations to evaluate the energy of the configuration, then we need $n \cdot 2^{1000} \sim 10^{301} n$ floating point operations
- The most powerful supercomputer today (Frontier, top500) can operate at about 1 ExaFlop/s = 10^{18} Flop/s, so it would take about $10^{283}n$ seconds to evaluate the exact solution (the age of the universe is about 4.3×10^{17} s)
- For classical statistical problems and problems that can be reduced to those (such as Euclidean lattice gauge theory) stochastic methods can often help to obtain approximate solutions

- For quantum problems (e.g. time evolution of a *quantum* Ising model would require exponentiating a $2^{N^3} \times 2^{N^3}$ matrix) or where Monte Carlo is inapplicable (often due to the *sign problem*) classical algorithms scale *exponentially* with the number of degrees of freedom
- Feynman (1982):

"The rule of simulation that I would like to have is that the number of computer elements required to simulate a large physical system is only to be proportional to the space-time volume of the physical system. I don't want to have an explosion."

- P. Benioff (1980), "The Computer as a Physical System: A Microscopic Quantum Mechanical Hamiltonian Model of Computers as Represented by Turing Machines"
- R.P. Feynman (1982), "Simulating Physics with Computers":
 "Can a *universal* quantum simulator be built?"
- S. Lloyd (1996), "Universal Quantum Simulators": "Yes"

• How can we make quantum computing work for the problems we want to solve?

- Is a non-empty set of V whose elements are called *vectors*, denoted |v⟩, with three operations:
 - addition +: $V \times V \rightarrow V$
 - negation $-: V \to V$
 - scalar multiplication $\cdot : C \times V \to V$

and a distinguished element zero vector $0 \in V$

- These operations and zero satisfy the following properties:
 - commutativity and associativity of the addition
 - zero is an additive identity and every vector has an inverse
 - scalar multiplication has 1 and respects complex multiplication
 - scalar multiplication distributes over addition and complex addition

- We are mainly interested in complex vector space *Cⁿ*: *n*-tuples of complex numbers
- In the simplest case, C^2 :

$$|z\rangle = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix}$$

- A spanning set is a set of vectors $|v_1\rangle, ..., |v_n\rangle$ such that for any vector $|v\rangle : |v\rangle = \sum_i a_i |v_i\rangle$
- For C^2 we can choose:

$$|v_1\rangle \equiv \begin{pmatrix} 1\\ 0 \end{pmatrix}, \qquad |v_2\rangle \equiv \begin{pmatrix} 0\\ 1 \end{pmatrix}$$

Complex vector space

- A set of non-zero $|v_1\rangle, ..., |v_n\rangle$ is *linearly dependent* if $a_1, ..., a_n$ exist that $a_1 |v_1\rangle + ... + a_n |v_n\rangle = 0$ with $a_i \neq 0$ for at least one value of *i*
- A set of linearly independent vectors that span vector space V is a *basis* in V
- The number of elements in the basis is the *dimension* of V
- In quantum computing we work with *finite-dimensional* vector spaces

• A *linear operator* between vector spaces V and W is any function $A: V \rightarrow W$ which is linear in its inputs:

$$A\left(\sum_{i} a_{i} |v_{i}\rangle\right) = \sum_{i} a_{i} A(|v_{i}\rangle)$$

- Normally use simpler notation: $A(|v\rangle) \equiv A |v\rangle$
- Let $|v_1\rangle, ..., |v_m\rangle$ be the basis for V and $|w_1\rangle, ..., |w_n\rangle$ for W, then for each *j* in the range 1,..., *m* there exist complex numbers $A_{1j}, ..., A_{nj}$ such that $A |v_j\rangle = \sum A_{ij} |w_i\rangle$
- A_{ij} is a matrix representation of the operator A

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• An *inner product* on a complex vector space V is a function $(..., ...): V \times V \rightarrow C$

that satisfies the following

- non-degenerate: $(|v\rangle, |v\rangle) \ge 0$ and $(|v\rangle, |v\rangle) = 0$ if and only if $|v\rangle = 0$
- respects addition and scalar multiplication
- skew-symmetric: $(|v\rangle, |w\rangle) = (|w\rangle, |v\rangle)^*$
- *V* with inner product is called *inner product space (Hilbert space)*
- The *dual vector* $\langle v |$ for $|v \rangle$ is a linear operator from the inner product space V to the complex numbers C such that $\langle v | (|w \rangle) \equiv \langle v | w \rangle \equiv (|v \rangle, |w \rangle)$
- Dirac notation: $|v\rangle ket$ -vector (column), $\langle v | bra$ -vector (row)

- Vectors $|v\rangle$ and $|w\rangle$ are *orthogonal* if $\langle v | w \rangle = 0$
- Norm of vector $|v\rangle$: $||v\rangle || \equiv \sqrt{\langle v | v \rangle}$
- A set of vectors $|i\rangle$ is *orthonormal* if each vector is a unit vector, $|||i\rangle ||=1$ and distinct vectors in the set are orthogonal, $\langle i|j\rangle = \delta_{ij}$
- Most of the time we use matrix representations of linear operators with respect to orthonormal bases
- The inner product on a Hilbert space with an orthonormal basis: $\langle v | w \rangle = \left(\sum_{i} v_i | i \rangle, \sum_{j} w_j | j \rangle \right) = \sum_{ij} v_i^* w_j \langle i | j \rangle = \sum_{i} v_i^* w_i$

Outer product representation

- Let $|v\rangle \in V$ and $|w\rangle \in W$. Define *outer product* as a linear operator $|w\rangle\langle v|: V \to W$ such that $(|w\rangle\langle v|)|v'\rangle \equiv |w\rangle\langle v|v'\rangle = \langle v|v'\rangle|w\rangle$
- Completeness relation: for any orthonormal basis $|i\rangle$ in V

$$\sum_{i} |i\rangle\langle i| = I$$

Quantum computing: data representation

- Classical computing: bits $b \in \{0,1\}$
- Quantum computing: qubits

 $|q\rangle \in C^2$

• Computational basis:

$$|0\rangle = \begin{pmatrix} 1\\ 0 \end{pmatrix} \qquad |1\rangle = \begin{pmatrix} 0\\ 1 \end{pmatrix}$$

• An arbitrary state is a *superposition*

$$|q\rangle = \alpha |0\rangle + \beta |1\rangle$$
 $|\alpha|^2 + |\beta|^2 = 1$

or

$$|q\rangle = e^{i\gamma} \left(\cos\frac{\theta}{2}|0\rangle + e^{i\phi}\sin\frac{\theta}{2}|1\rangle\right)$$

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Bloch sphere representation

- Drop the global phase γ it cancels in the observables
- The angles cover the sphere: θ ∈ [0,π], φ ∈ [0,2π), so we can treat them as spherical coordinates

