# Large Scale Shell-Model Calculations for Open-shell nuclei



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## LARGE SCALE SHELL-MODEL CALCULATIONS FOR OPEN-SHELL NUCLEI

#### Part I: The BIGSTICK shell model code

+ W. Erich Ormand (LLNL), Ken McElvain (UC Berkeley), Hongzhang Shan (LBL)

Part II: Applications

II a: Transitions and the Brink-Axel hypothesis

+ Michael K. G. Kruse (LLNL), W. Erich Ormand (LLNL) and Micah Schuster (SDSU)

II b: *ab initio* Gamow-Teller transitions (in progress)

II c: L-S decomposition of ab initio nuclides

### EXECUTIVE SUMMARY ON THE BIGSTICK CODE

Many-fermion code: 2<sup>nd</sup> generation after REDSTICK code (started in *Baton Rouge, La.*)

Uses "factorization" algorithm: Johnson, Ormand, and Krastev,

Comp. Phys. Comm. 184, 2761(2013)

Arbitrary single-particle radial waveforms

Allows local or nonlocal two-body interaction

Three-body forces implemented and validated

Applies to both nuclear and atomic cases

Runs on both desktop and parallel machines

<u>--can run at least dimension 300M+ on desktop</u>

-- has done dimension 9 billion+ on supercomputers

Inline calculations of one-body density matrices, single-particle occupations,

(+ options to compute strength functions via Lanczos trick, etc.)

Will add 2-body non-scalar transition operators later this year

45 kilolines of code Fortran 90 + MPI + OpenMP

Plan to release beta version later this year...followed by CPC pub

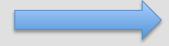
#### THE BASIC PROBLEM

The matrix formalism:

$$\begin{aligned} \hat{\mathbf{H}} |\Psi\rangle &= E |\Psi\rangle \\ |\Psi\rangle &= \sum_{\alpha} c_{\alpha} |\alpha\rangle \qquad H_{\alpha\beta} &= \langle \alpha | \hat{\mathbf{H}} |\beta\rangle \\ \sum_{\beta} H_{\alpha\beta} c_{\beta} &= E c_{\alpha} \quad \text{if} \qquad \langle \alpha |\beta\rangle &= \delta_{\alpha\beta} \end{aligned}$$

#### THE BASIC PROBLEM

Find extremal eigenvalues of very large, very sparse Hermitian matrix



Lanczos algorithm

fundamental operation is matrix-vector multiply

$$|\mathbf{A}\vec{v}_{1}| = \alpha_{1}\vec{v}_{1} + \beta_{1}\vec{v}_{2}$$

$$|\mathbf{A}\vec{v}_{2}| = \beta_{1}\vec{v}_{1} + \alpha_{2}\vec{v}_{2} + \beta_{2}\vec{v}_{3}$$

$$|\mathbf{A}\vec{v}_{3}| = \beta_{2}\vec{v}_{2} + \alpha_{3}\vec{v}_{3} + \beta_{3}\vec{v}_{4}$$

$$|\mathbf{A}\vec{v}_{4}| = \beta_{3}\vec{v}_{3} + \alpha_{4}\vec{v}_{4} + \beta_{4}\vec{v}_{5}$$
matrix-vector multiply

Lanczos algorithm!

### A Sparse Matrix, but....

Despite sparsity, nonzero matrix elements can require TB of storage

### How the basis states are represented

Product wavefunction ("Slater Determinant")

$$\Psi(\vec{r}_1, \vec{r}_2, \vec{r}_3 \dots) = \phi_{n_1}(\vec{r}_1)\phi_{n_2}(\vec{r}_2)\phi_{n_3}(\vec{r}_3)\dots\phi_{n_N}(\vec{r}_N)$$

Each many-body state can be *uniquely* determined by a list of "occupied" single-particle states = "occupation representation"

$$|\alpha\rangle = \hat{a}_{n_1}^+ \hat{a}_{n_2}^+ \hat{a}_{n_3}^+ \dots \hat{a}_{n_N}^+ |0\rangle$$

### A SPARSE MATRIX, BUT....

Despite sparsity, nonzero matrix elements can require TB of storage

### Typical dimensions and sparsity

Nuclide	valence space	valence Z	valence N	basis dim	sparsity $\binom{0}{0}$	
$^{20}\mathrm{Ne}$	"sd"	2	2	640	10	
$^{25}{ m Mg}$	"sd"	4	5	44,133	0.5	
<sup>49</sup> Cr	"pf"	4	5	6M	0.01	
$^{56}\mathrm{Fe}$	"pf"	6	10	500M	2x10 <sup>-4</sup>	
$^{12}\mathrm{C}$	$N_{\text{max}} = 8$	6	6	600M	4x10 <sup>-4</sup>	2-body force
$^{12}C$	$N_{\text{max}} = 8$	6	6	600 <b>M</b>	$2x10^{-2}$	3-body force

### A Sparse Matrix, but....

Despite sparsity, nonzero matrix elements can require TB of storage

Nuclide	Space	Basis dim	matrix store
<sup>56</sup> Fe	pf	501 M	4.2 Tb
<sup>7</sup> Li	N <sub>max</sub> =12	252 M	3.6 Tb
<sup>7</sup> Li	N <sub>max</sub> =14	1200 M	23 Tb
<sup>12</sup> C	N <sub>max</sub> =6	32M	0.2 Tb
<sup>12</sup> C	$N_{\text{max}} = 8$	590M	5 Tb
<sup>12</sup> C	N <sub>max</sub> =10	7800M	111 Tb
<sup>16</sup> O	$N_{\text{max}} = 6$	26 M	0.14 Tb
<sup>16</sup> O	N <sub>max</sub> =8	990 M	9.7 Tb

### RECYCLED MATRIX ELEMENTS

Only a fraction of matrix elements are unique; most are reused.

Reuse of matrix elements understood through *spectator* particles.

# of nonzero matrix elements vs. # unique matrix elements

Nuclide	valence space	valence Z	valence N	# nonzero	# unique
$^{28}\mathrm{Si}$	"sd"	6	6	$26 \times 10^6$	3600
52Fe	"pf"	6	6	$90 \times 10^9$	21,500

This suggests one can reduce storage of matrix elements...

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

A quantum number is the eigenvalue of an operator

generally a operator that exactly commutes with the Hamiltonian

e.g. angular momentum  $\mathbf{J}^2$  and z-component  $\mathbf{J}_z$ 

$$\hat{J}^2 |\Psi\rangle = J(J+1)|\Psi\rangle$$
  $\hat{J}_z |\Psi\rangle = M|\Psi\rangle$ 

Reuse can be **exploited using exact factorization** enforced through *Abelian* (additive/multiplicative) *quantum numbers* 

### A quantum number is the eigenvalue of an operator

For composite systems, one can apply the operator to each component separately:

$$\hat{O}|\Psi\rangle = (\hat{O}_1 + \hat{O}_2 + \hat{O}_3 + \ldots)(|\Psi_1\rangle \otimes |\Psi_2\rangle \otimes |\Psi_3\rangle \otimes \ldots)$$

Sometimes the total quantum number is a simple sum/product as is the case for  $J_z$  or parity....

$$\hat{J}_z |\Psi\rangle = M |\Psi\rangle = (m_1 + m_2 + m_3 + \ldots) |\Psi\rangle$$

...but in other cases the addition is complicated (e.g. for  $\mathbf{J}^2$ )

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

I consider composite many-fermion systems, in particular those with 2 major components *protons* and *neutrons* 

or

spin-up and spin-down electrons

$$|\Psi\rangle = |\Psi_1\rangle \otimes |\Psi_2\rangle$$

Each component itself is a Slater determinant which is composed of many particles

$$\hat{J}_z |\Psi\rangle = M |\Psi\rangle$$
  $M = M_1 + M_2$  
$$M_1 = m_1^{(1)} + m_1^{(2)} + m_1^{(2)} + \dots$$

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

Because the M values are discrete integers or half-integers (-3, -2, -1, 0, 1, 2, ... or -3/2, -1/2, +1/2, +3/2...) we can organize the basis states in discrete *sectors* 

Example: 2 protons, 4 neutrons, total M = 0

$$M_{7}(\pi) = -4$$

$$M_{7}(v) = +4$$

$$M_{7}(\pi) = -3$$

$$M_{7}(v) = +3$$

$$M_z(\pi) = -2$$

$$M_z(\upsilon) = +2$$

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

In fact, we can see an example of factorization here because all proton Slater determinants in one M-sector *must* combine with all the conjugate neutron Slater determinants

Example: 2 protons, 4 neutrons, total M = 0

$$M_{7}(\pi) = -4: 2 SDs$$

$$M_z(v) = +4: 24 SDs$$

48 combined

$$M_{7}(\pi) = -3:4 \text{ SDs}$$

$$M_7(v) = +3:39 SDs$$

156 combined

$$M_{7}(\pi) = -2: 9 SDs$$

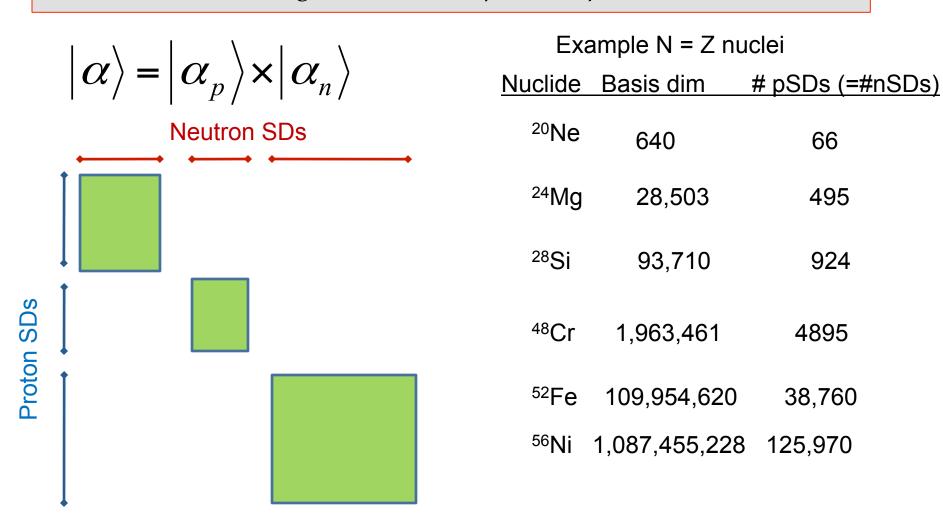
$$M_{7}(v) = +2:60 SDs$$

540 combined

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

In fact, we can see an example of factorization here because all proton Slater determinants in one M-sector *must* combine with all the conjugate neutron Slater determinants

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

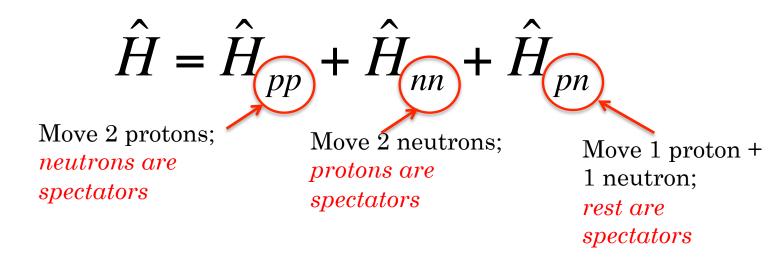


# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

Factorization allows us to keep track of all basis states without writing out every one explicitly

-- we only need to write down the proton/neutron components

### The same trick can be applied to matrix-vector multiply



# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*



Move 2 protons;

neutrons are spectators\_\_\_

Example: 2 protons, 4 neutrons, total M = 0

$$M_z(\pi) = -4: 2 SDs$$

 $M_z(v) = +4: 24 SDs$ 

48 combined

There are potentially  $48 \times 48$  matrix elements But for  $H_{pp}$  at most  $4 \times 24$  are nonzero and we only have to look up 4 matrix elements

Advantage: we can store 98 matrix elements as 4 matrix elements and avoid 2000+ zero matrix elements.

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

$$M_z(\pi) = -4: 2 SDs$$

$$M_z(v) = +4: 24 SDs$$

48 combined

$$\begin{vmatrix} \boldsymbol{v}_{1} \rangle & \boldsymbol{H}_{pp} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{1} \rangle = \boldsymbol{H}_{11} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{1} \rangle + \boldsymbol{H}_{12} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{1} \rangle$$

$$\begin{vmatrix} \boldsymbol{v}_{2} \rangle & \boldsymbol{H}_{pp} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{1} \rangle = \boldsymbol{H}_{12} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{1} \rangle + \boldsymbol{H}_{12} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{1} \rangle$$

$$\begin{vmatrix} \boldsymbol{v}_{2} \rangle & \boldsymbol{H}_{pp} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{1} \rangle = \boldsymbol{H}_{12} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{1} \rangle + \boldsymbol{H}_{22} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{1} \rangle$$

$$\begin{vmatrix} \boldsymbol{v}_{3} \rangle & \boldsymbol{H}_{pp} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{2} \rangle = \boldsymbol{H}_{11} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{2} \rangle + \boldsymbol{H}_{12} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{2} \rangle$$

$$\vdots$$

$$\vdots$$

$$|\boldsymbol{v}_{24} \rangle & \boldsymbol{H}_{pp} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{24} \rangle = \boldsymbol{H}_{11} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{24} \rangle + \boldsymbol{H}_{12} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{24} \rangle$$

$$\boldsymbol{H}_{pp} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{24} \rangle = \boldsymbol{H}_{12} | \boldsymbol{\pi}_{1} \rangle | \boldsymbol{v}_{24} \rangle + \boldsymbol{H}_{22} | \boldsymbol{\pi}_{2} \rangle | \boldsymbol{v}_{24} \rangle$$

Advantage: we can store 98 matrix elements as 4 matrix elements and avoid 2000+ zero matrix elements.

# Reuse can be **exploited using exact factorization** enforced through *additive/multiplicative quantum numbers*

### Comparison of nonzero matrix storage with factorization

Nuclide	Space	Basis dim	matrix store	factorization
<sup>56</sup> Fe	pf	501 M	290 Gb	0.72 Gb
<sup>7</sup> Li	N <sub>max</sub> =12	252 M	3600 Gb	96 Gb
<sup>7</sup> Li	N <sub>max</sub> =14	1200 M	23 Tb	624 Gb
<sup>12</sup> C	N <sub>max</sub> =6	32M	196 Gb	3.3 Gb
<sup>12</sup> C	N <sub>max</sub> =8	590M	5000 Gb	65 Gb
<sup>12</sup> C	N <sub>max</sub> =10	7800M	111 Tb	1.4 Tb
<sup>16</sup> O	N <sub>max</sub> =6	26 M	142 Gb	3.0 Gb
<sup>16</sup> O	N <sub>max</sub> =8	990 M	9700 Gb	130 Gb

### Comparison of nonzero matrix storage with factorization

### <sup>7</sup>Li

Space	Basis dim	matrix store (2-body)	factorization (2-body)	matrix store (3-body)	factorization (3-body)
N <sub>max</sub> =8	6 M	36 Gb	1.5 Gb	1 Tb	26 Gb
N <sub>max</sub> =10	43 M	430 Gb	10 Gb	170 Tb	250 Gb
N <sub>max</sub> =12	250 M	4 Tb	60 Gb		

Space	Basis dim	matrix store (2-body)	factorization (2-body)	matrix store (3-body)	factorization (3-body)
N <sub>shell</sub> =3	0.4 M	0.8 Gb	6 Mb	10 Gb	44 Mb
N <sub>shell</sub> =4	45 M	330 Gb	0.3 Gb	9 Tb	4 Gb
N <sub>shell</sub> =5	2 G	38 Tb	16 Gb	2 Pb	140 Gb
N <sub>shell</sub> =6	50 G	2 Pb	87 Gb	170 Pb	3 Tb

### PARALLEL IMPLEMENTATION

Factorization makes it easier to compute workload and distribute across multiple nodes

length of sides =
information to be stored

length of sides = information to be stored

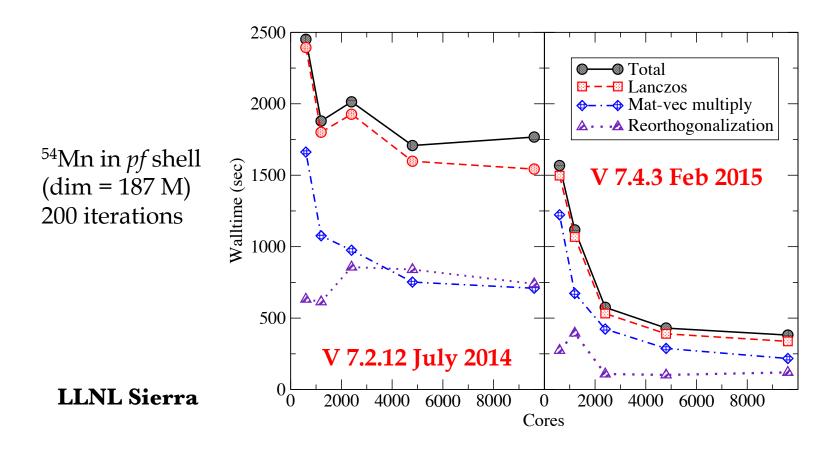
Area = total # of operations

We can compute the number of operations without actually counting them!

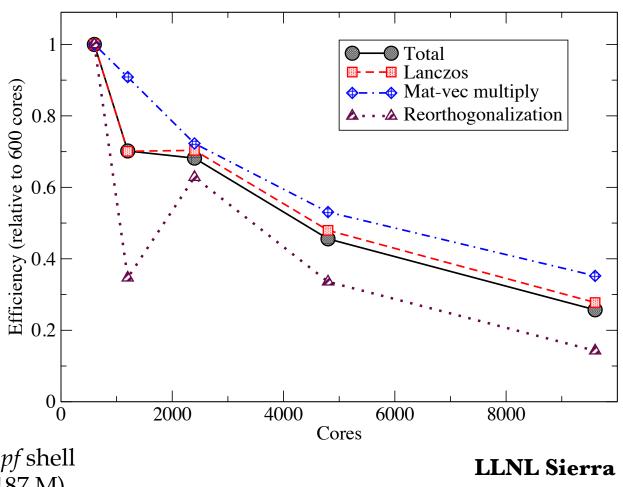
Then we can easily divide the work across compute nodes



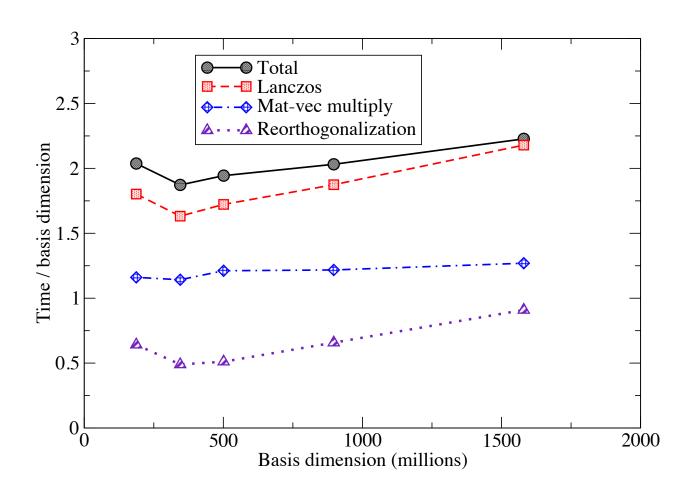
Over the past year we have dramatically improved our parallel performance (mostly through better use of MPI) due to Ken McElvain, UC Berkeley grad student



## Strong scaling

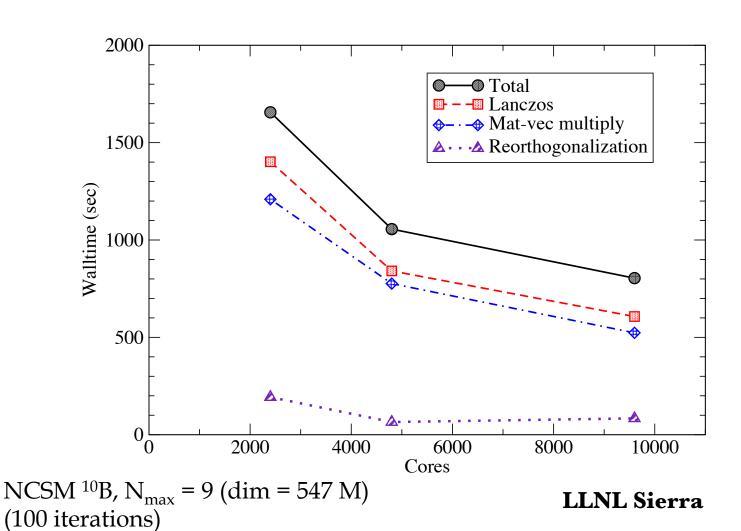


 $^{54}$ Mn in pf shell (dim = 187 M) 200 iterations



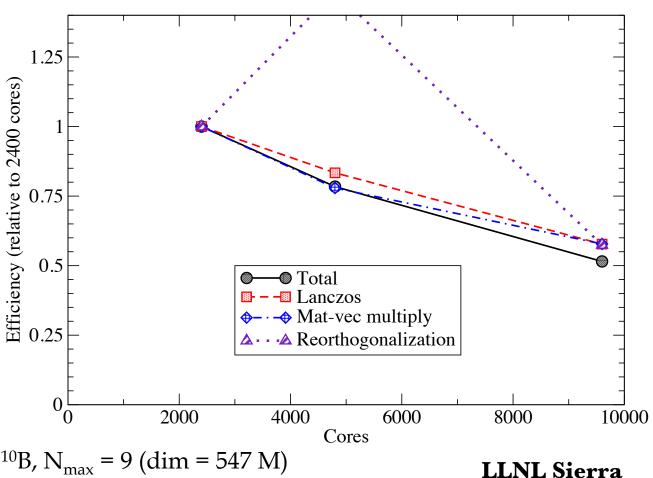
pf shell nuclides(200 iterations)800 MPI procs x 12 OpenMP threads

LLNL Sierra V 7.4.3 Feb 2015

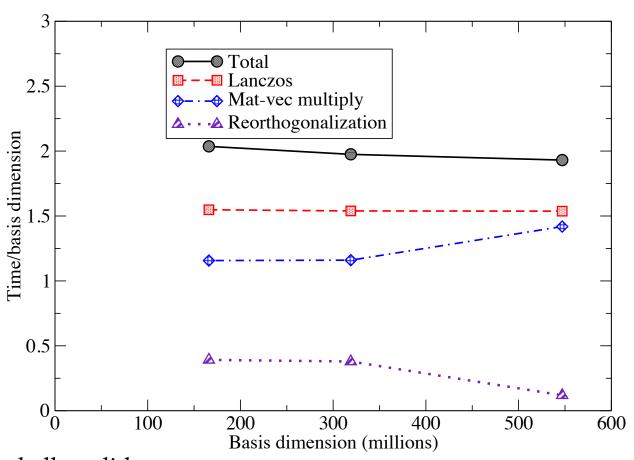


800 MPI procs x 12 OpenMP threads

## Strong scaling



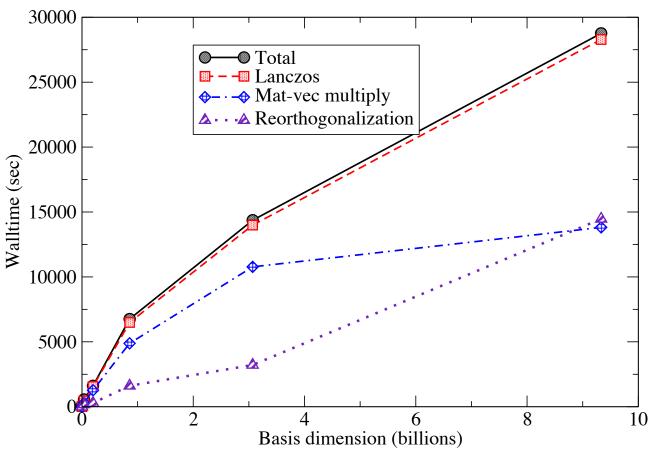
NCSM  $^{10}$ B, N<sub>max</sub> = 9 (dim = 547 M) (100 iterations) 800 MPI procs x 12 OpenMP threads



NCSM *p*-shell nuclides (100 iterations) 800 MPI procs x 12 OpenMP threads

LLNL Sierra

#### Science runs! Dark matter scattering cross-sections



Xe isotopes with <sup>100</sup>Sn core (140-250 iterations)

6000-12000 MPI procs x 4-6 OpenMP threads

LBL/NERSC Edison

### FUTURE WORK

### Improved memory load:

Because we chunk data based upon physics (quantum numbers), the natural distribution is irregular. Nonetheless we understand where and (mostly) how to improve the distribution of memory load:

- 2<sup>nd</sup> generation fragmentation of Lanczos vectors (DONE)
- 2<sup>nd</sup> generation distribution of "jump" arrays (almost finished)
- 2<sup>nd</sup> generation storage of uncoupled matrix elements (in planning stage)

### Improve work load balance:

We think we understand how and why the work load balance loses efficiency: different ordering of loops and irregular loop sizes. We are gathering data (H. Shan, LBL).

### Pushing to larger cases

We plan to go to dim ~ 24 billion this summer (< 6000 MPI nodes)

We plan to go to dim ~ 100 billion in the next year



"It's not enough to just show up. You have to have a business plan."

# **APPLICATIONS**

# APPLICATIONS

IIa: Transitions and the Brink-Axel hypothesis

+ Michael K. G. Kruse (LLNL), W. Erich Ormand (LLNL), and Micah Schuster (SDSU)

## LARGE SCALE SHELL-MODEL CALCULATIONS FOR OPEN-SHELL NUCLEI

### Transitions and the Brink-Axel hypothesis

+ Michael K. G. Kruse (LLNL), W. Erich Ormand (LLNL), and Micah Schuster (SDSU)

Brink-Axel hypothesis (D. Brink, D. Phil. thesis, Oxford University (unpublished), 1955; P. Axel, Phys. Rev. 126, 671 (1962)):

If the ground state has a giant dipole resonance (GDR), then excited states should have GDR

and

because the GDR is a collective proton-versus-neutrons oscillations, the GDR should be insensitive to the initial state. Electric dipole

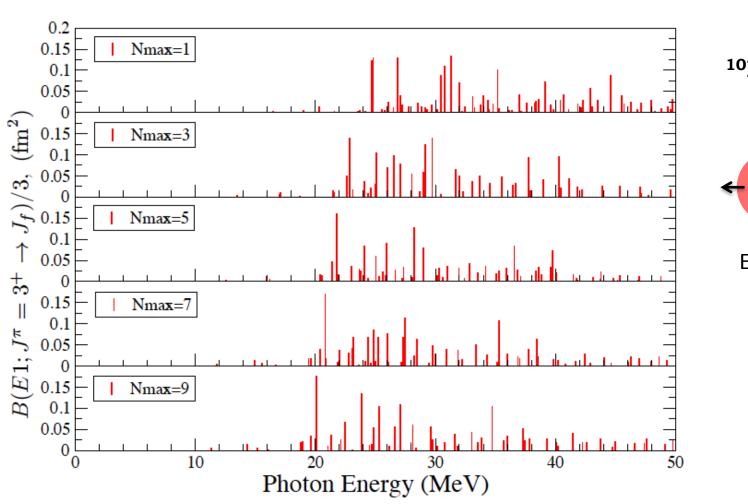
$$S(E_i, E_x) = \sum_{f} |\langle f | \hat{T} | i \rangle | \delta(E_x - E_f + E_i)$$

"Transition strength function"

Brink-Axel: " $S(E_i, E_x)$  independent of  $E_i$ "

## LARGE SCALE SHELL-MODEL CALCULATIONS FOR OPEN-SHELL NUCLEI

Kruse, Ormand, and Johnson: arXiv:1502:03464



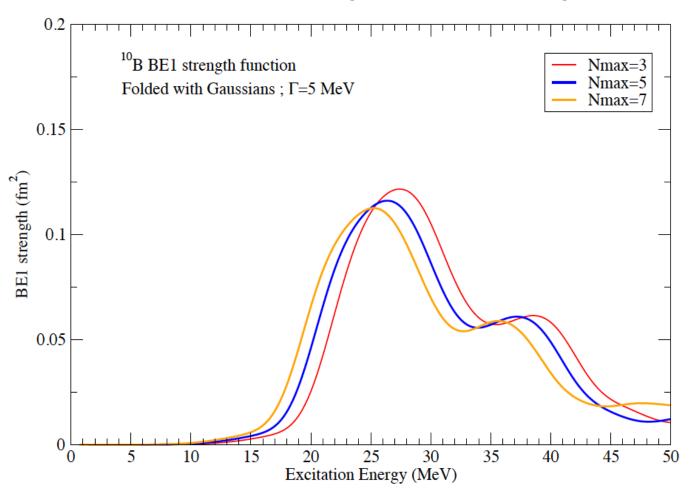
<sup>10</sup>B E1 response



Electric dipole

## LARGE SCALE SHELL-MODEL CALCULATIONS FOR OPEN-SHELL NUCLEI

### BE1 strength with increasing basis size



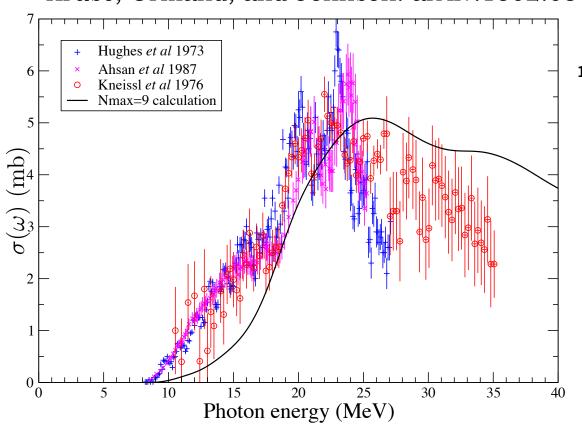
Strength distribution shape is robust in Nmax.

Slowly moves down in energy as a function of Nmax.

How to extrapolate this distribution?

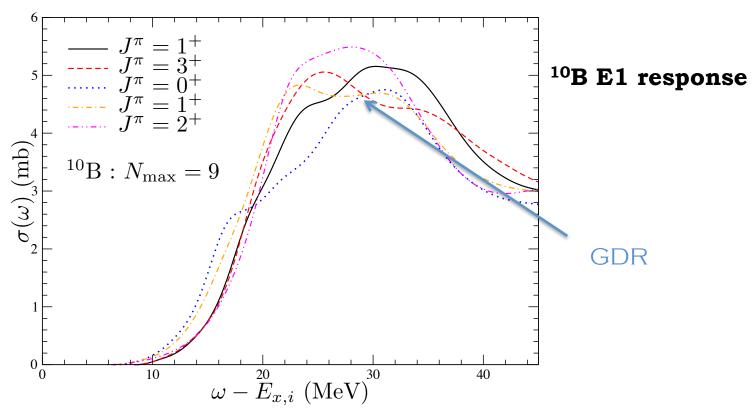
Perhaps it is best to extrapolate centroids?

Kruse, Ormand, and Johnson: arXiv:1502:03464

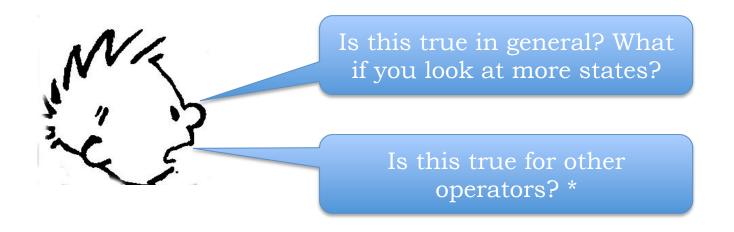


<sup>10</sup>B E1 response

Kruse, Ormand, and Johnson: arXiv:1502:03464



Brink-Axel: " $S(E_i, E_x)$  independent of  $E_i$ "

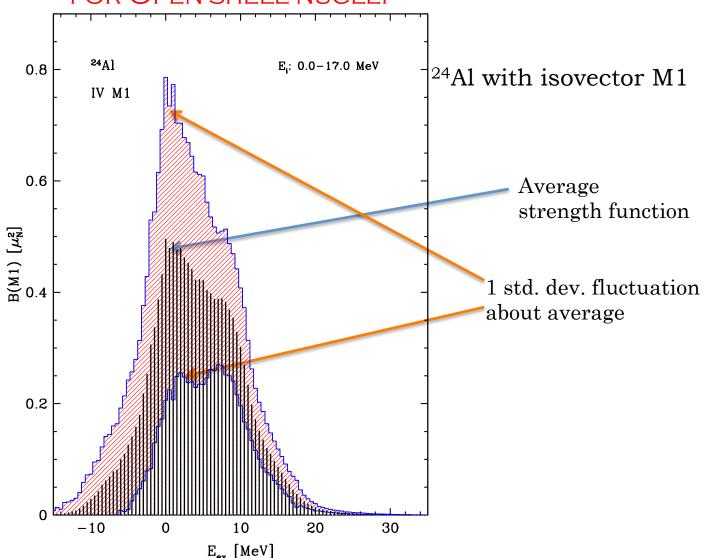


\* Some evidence to the contrary (with Gamow-Teller operator): Frazier, Brown, Millener, and Zelevinsky, Phys. Lett B **414**, 7 (1997); Misch, Fuller, and Brown, PRC 90, 065808 (2014)

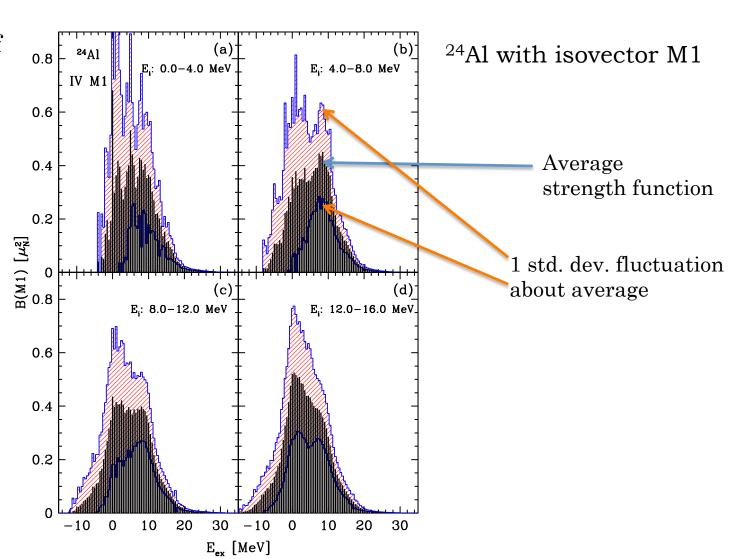
Some preliminary work by Micah Schuster: phenomenological calculations in sd-shell where we can compute hundreds of initial states

Took energy bins of initial states, computed strength functions, and computed average strength function + fluctuations about average

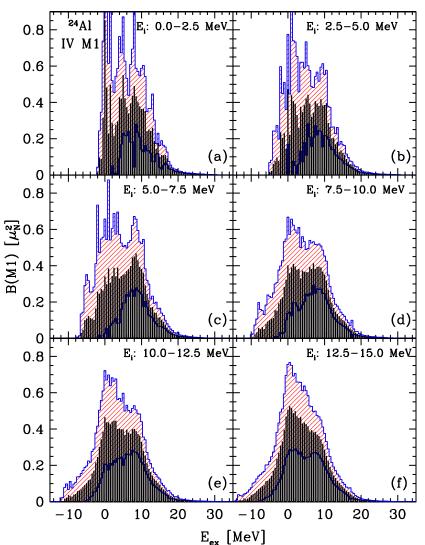
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Took energy bins of initial states, computed strength functions, and computed average strength function + fluctuations about average



Took energy bins of initial states, computed strength functions, and computed average strength function + fluctuations about average



<sup>24</sup>Al with isovector M1

 $^{23}Mg$ 0.8  $E_{i}: 0.0-5.0 \text{ MeV}$ E<sub>i</sub>: 5.0-10.0 MeV IV M1 0.6 0.4 0.2  $\begin{array}{c} B(M1) \ [\mu_N^2] \\ 0 \\ 0 \end{array}$ E;: 15.0-20.0 MeV E<sub>i</sub>: 10.0-15.0 MeV. 0.6 0.4 0.2 -100 10 20 30 -100 10 20 30

 $E_{ex}$  [MeV]

(b) 23Mg with isovector M1

Looks like large fluctuations about the average; can we characterize / quantify this?



The total strength (or *non-energy-weighted sum rule*) can be computed as a simple expectation value

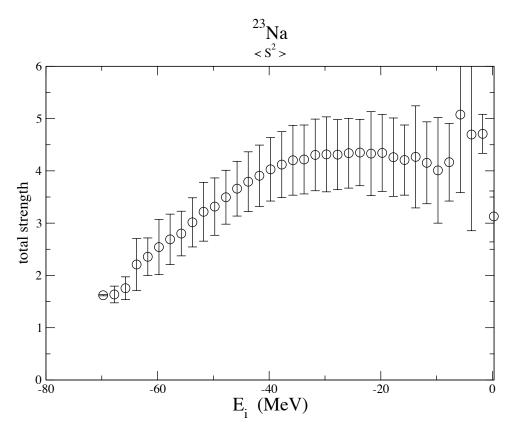
Looks like large fluctuations about the average; can we characterize / quantify this?

$$S_0(E_i) = \int S(E_i, E_x) dE_x = \sum_f |\langle f | \hat{T} | i \rangle| = \langle i | \hat{T}^+ T | i \rangle$$



The total strength (or *non-energy-weighted sum rule*)

$$\int S(E_i, E_x) dE_x = \sum |\langle f | \hat{T} | i \rangle| = \langle i | \hat{T}^+ T | i \rangle$$



Furthermore, the smooth secular behavior is easily understood through spectral distribution theory of J. B. French et al

Average expectation value is just a trace!

$$\langle \hat{O} \rangle = \frac{1}{N} \sum_{i} \langle i | O | i \rangle = \frac{1}{N} tr (\hat{O})$$



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Average expectation value is just a trace!

$$\langle \hat{O} \rangle = \frac{1}{N} \sum_{i} \langle i | O | i \rangle = \frac{1}{N} tr (\hat{O})$$

(Linear) energy dependence is also a trace!

$$\frac{1}{N} \sum_{i} E_{i} \langle i | O | i \rangle = \frac{1}{N} \sum_{i} \langle i | OH | i \rangle = \frac{1}{N} tr \left( OH \right)$$

Slope is given by < OH > - < O > < H >



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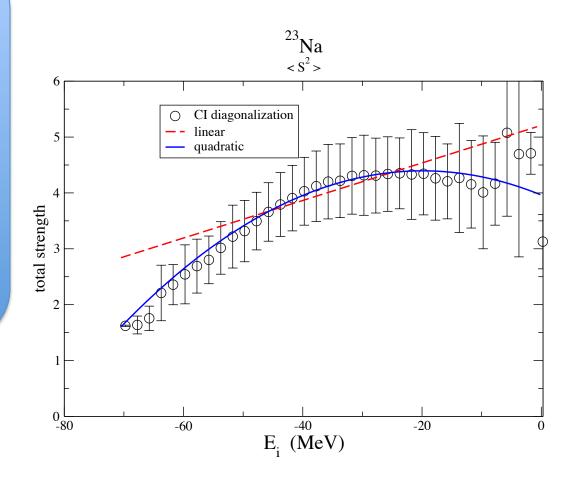
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$$\frac{1}{N} \sum_{i} E_{i} \langle i | O | i \rangle = \frac{1}{N} \sum_{i} \langle i | OH | i \rangle = \frac{1}{N} tr \left( OH \right)$$

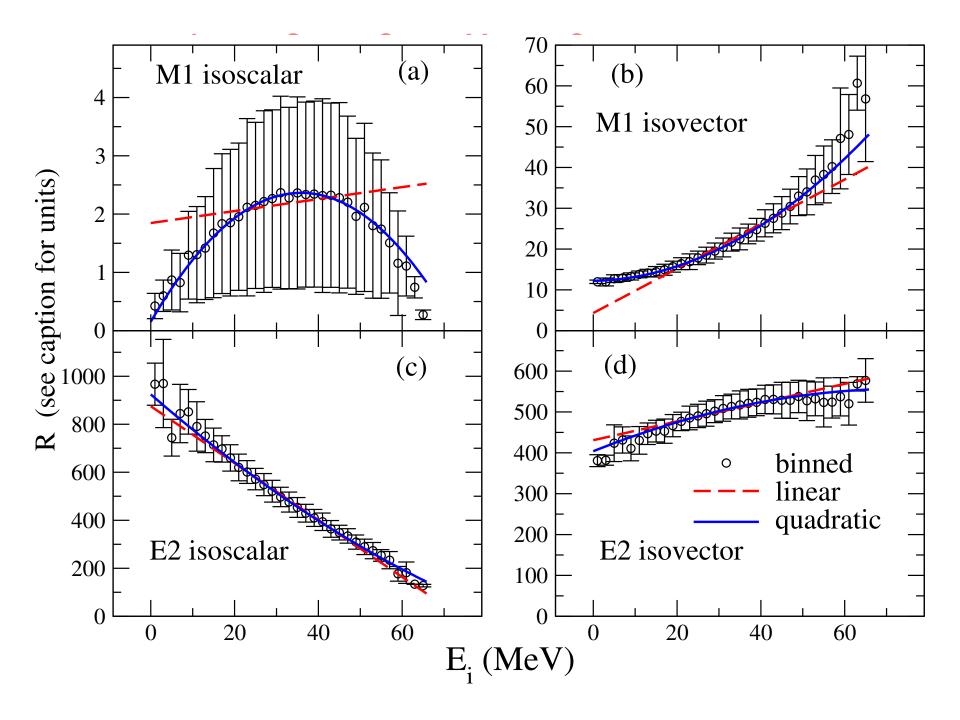


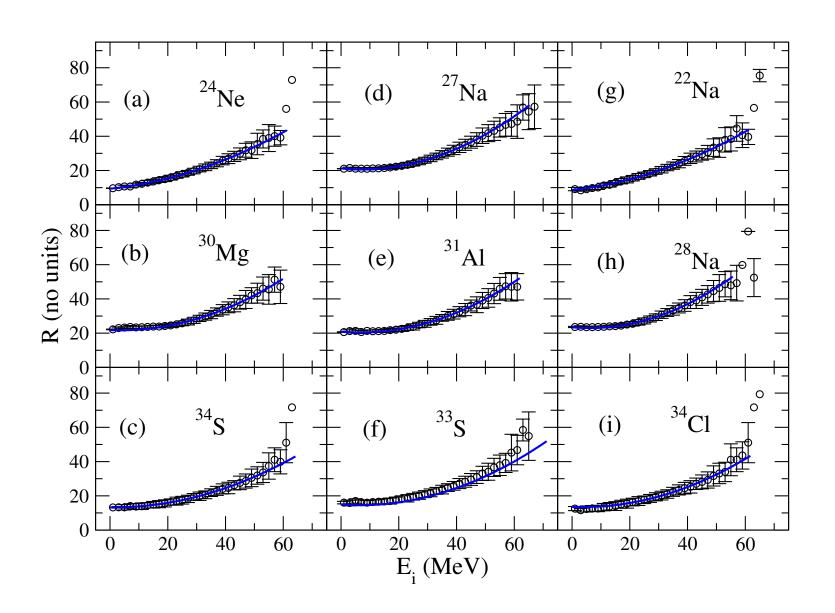
From this we can derive the secular behavior of expectation values

Furthermore, the smooth secular behavior is easily understood through spectral distribution theory of J. B. French et al

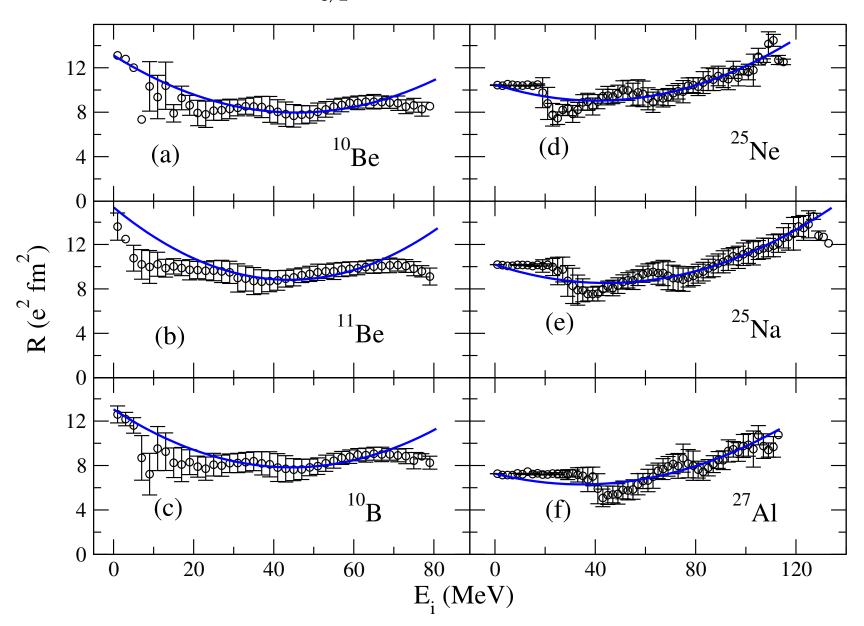








p-s $d_{5/2}$  shell, isovector E1



What we do learn from this?

The generalized Brink-Axel hypothesis (for arbitrary operators) is *wrong*!

- -- total strength evolves with initial (parent) energy
- -- significant fluctuations even for nearby parent states

We can understand this through *spectral* distribution theory, that is, traces of operators (weighted by the energy);

A lack of energy dependence can occur *only* if

$$< OH > - < O > < H > = 0$$



### APPLICATIONS

IIb: : ab initio Gamow-Teller transitions

Part IIb: ab initio Gamow-Teller transitions

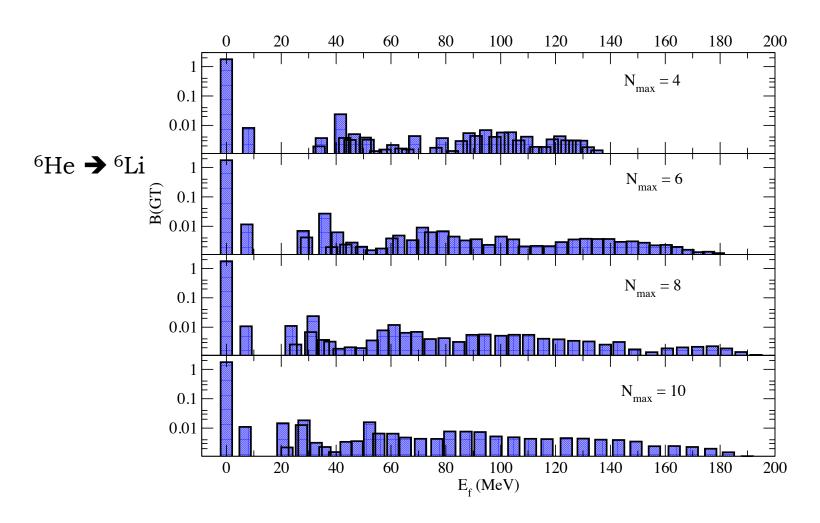
- Gamow-Teller important for weak physics, astrophysics
- Avoids dependence on radial wavefunctions (at lowest order); mostly SU(4) irreps; Ikeda sum rule strong constraint
- Consistent quenching of coupling—exchange currents, or what?
- What about 0-neutrino double-beta decay?

#### Two recent highlights:

Anomalously long <sup>14</sup>C half-life (Maris, Vary, Navratil, Ormand, Nam, Dean) Phys. Rev. Lett. 106, 202502 (2011): 'accidental' cancellation of matrix elements driven by 3-body force

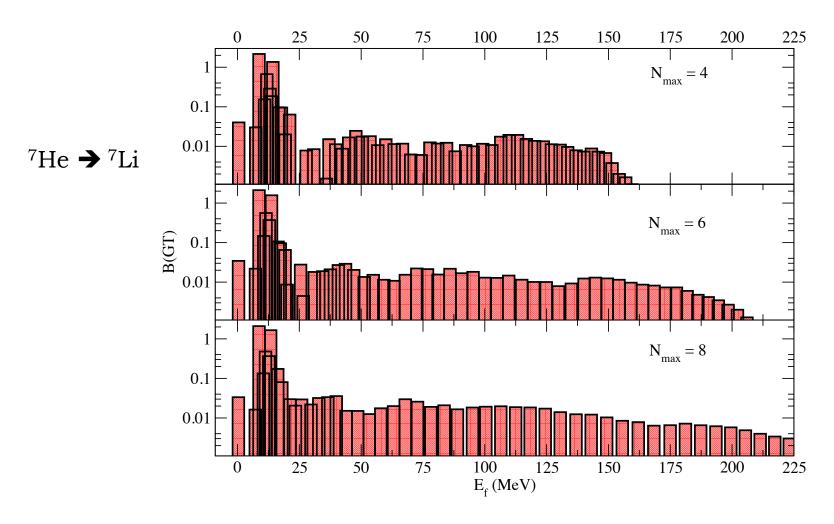
Exchange current corrections from EFT (quenching of about 0.8):

- S. Vaintraub, N. Barnea, and D. Gazit, Phys. Rev. C 79, 065501 (2009);
- J. Menendez, D. Gazit, and A. Schwenk, Phys. Rev. Lett **107**, 062501 (2011)



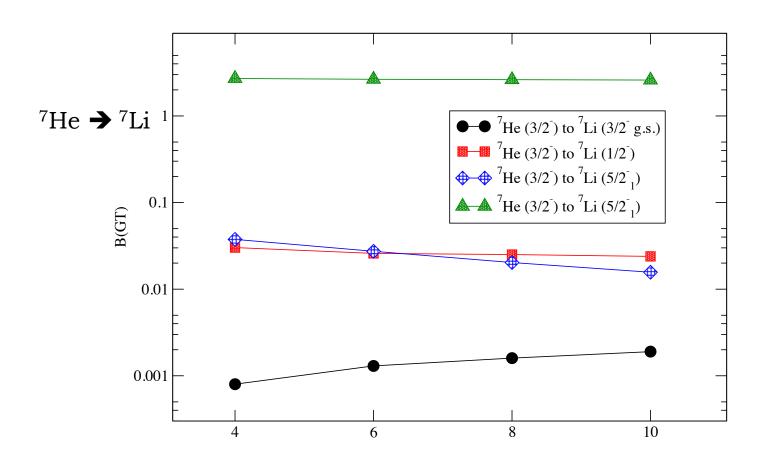
Preliminary!

Chiral 2-body forces SRG evolved to  $\lambda=2~fm^{-1}$ )

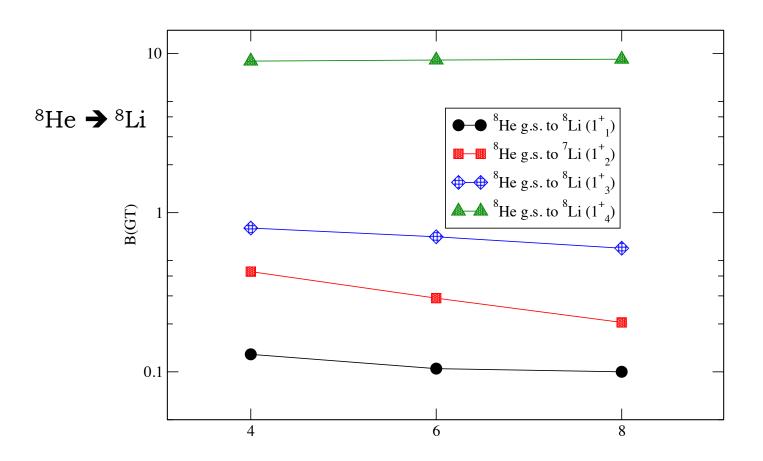


Preliminary!

(Run on desktop machine with BIGSTICK)



#### Preliminary!



#### Preliminary!

Need to run higher  $N_{max}$  (on supercomputers) but ...

Despite being a "simple" operator, transition matrix elements of Gamow-Teller ( $\sigma\tau$ ) do not have simple behavior:

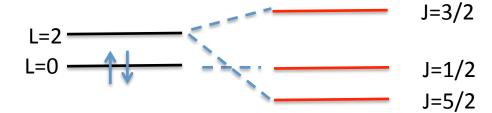
- $\bullet \;\;$  Some transitions quickly converge as we go up in  $N_{\text{max}\prime}$  others not
- Should be investigated by doing L-S/SU(4) decomposition
- Effect of 3-body forces likely important
- More work on chiral EFT exchange forces should be done
- Likely strong implications for  $0v-\beta\beta$  matrix elements...

### APPLICATIONS

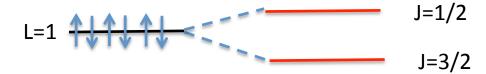
IIc: :Spin-orbit decomposition of ab initio nuclides

C. W. J, Phys. Rev. C 91, 034313 (2015).

#### Atoms: Nuclei:



#### *Spin* is minor in atomic physics...





(Niels Bohr) (E. Schrodinger)

...but crucial in nuclear physics...



(Maria Goeppert-Mayer)

#### j-j versus L-S



#### How good is j-j coupling?

(Calculations are standard configurationmixing: diagonalization of Hamiltonian

in *m*-scheme Slater determinants, in single major harmonic oscillator shell)

\_\_\_\_\_ J=1/2

J=3/2

\_\_\_\_\_\_ J=5/2

\_\_\_\_\_ J=1/2

\_\_\_\_\_ J=3/2

\_\_\_\_\_ J=1/2

Oh no! I guess there is a lot of configuration mixing!



Nuclide	Model space	Interaction	g.s. =
<sup>48</sup> Ca	pf	KB3G	90 % (0f <sub>7/2</sub> ) <sup>8</sup>
<sup>24</sup> O	sd	USDB	91% (0d <sub>5/2</sub> ) <sup>6</sup> (1s <sub>½</sub> ) <sup>2</sup>
<sup>22</sup> O	sd	USDB	75% (0d <sub>5/2</sub> ) <sup>6</sup>
<sup>8</sup> He	р	Cohen- Kurath	53 % (0p <sub>3/2</sub> ) <sup>4</sup>

Nuclide	Model space	Interaction	g.s. =
<sup>32</sup> S	sd	USDB	29 % (0d <sub>5/2</sub> ) <sup>12</sup> (1s <sub>½</sub> ) <sup>4</sup>
<sup>28</sup> Si	sd	USDB	21% (0d <sub>5/2</sub> ) <sup>12</sup>
<sup>12</sup> C	р	Cohen- Kurath	37% (0p <sub>3/2</sub> ) <sup>8</sup>

Let's see if there is a simpler picture, such as L-S coupling.

Nuclide	Model space	Interaction	g.s. =	g.s. =
<sup>48</sup> Ca	pf	KB3G	90 % (0f <sub>7/2</sub> ) <sup>8</sup>	20% L = 0
<sup>24</sup> O	sd	USDB	91% (0d <sub>5/2</sub> ) <sup>6</sup> (1s <sub>½</sub> ) <sup>2</sup>	34% L = 0
<sup>22</sup> O	sd	USDB	75% (0d <sub>5/2</sub> ) <sup>6</sup>	38% L = 0
<sup>8</sup> He	р	Cohen-Kurath	53 % (0p <sub>3/2</sub> ) <sup>4</sup>	96% L = 0
<sup>32</sup> S	sd	USDB	29 % (0d <sub>5/2</sub> ) <sup>12</sup> (1s <sub>1/2</sub> ) <sup>4</sup>	34% L = 0
<sup>28</sup> Si	sd	USDB	21% (0d <sub>5/2</sub> ) <sup>12</sup>	36% L = 0
<sup>12</sup> C	р	Cohen-Kurath	37% (0p <sub>3/2</sub> ) <sup>8</sup>	82% L = 0

This illustrates a (once) well-known fact: that L-S coupling is a better approximation in the p-shell than j-j coupling.



# Let's now do L-S decomposition of *ab initio p*-shell wavefunctions

#### Why?

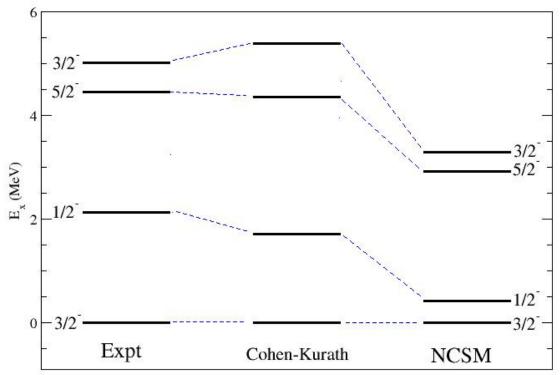
- -- To see if this pattern holds for *ab initio* interactions
  - -- How well do phenomenological interactions match ab initio?
- -- Crucially, we know the 3-body forces strongly affects the spin-orbit force. Can we see this happen directly?

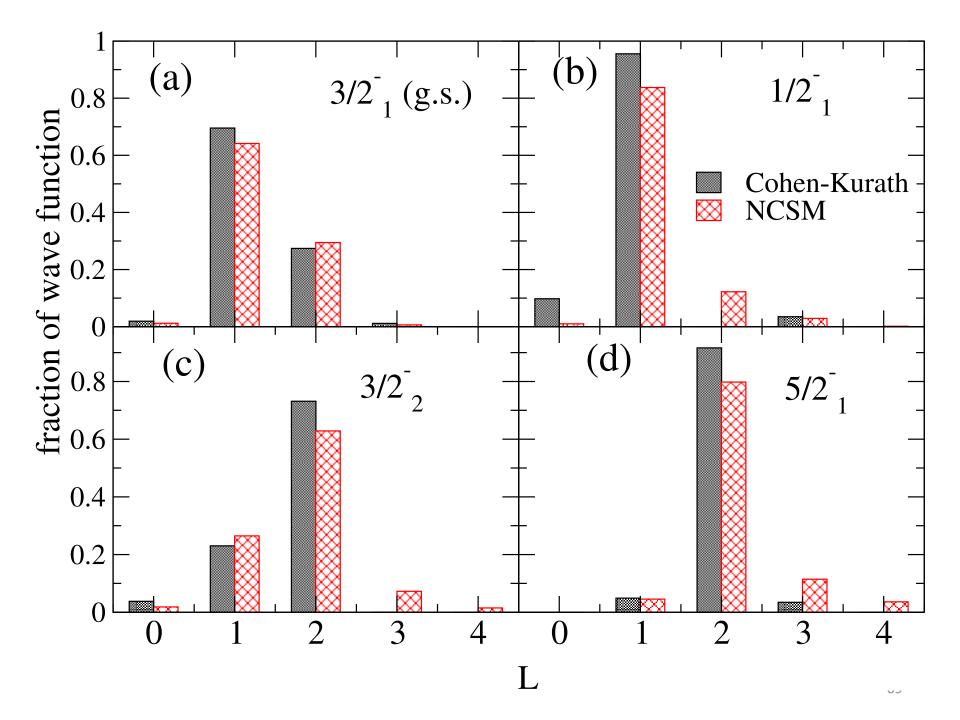
*Note:* In this talk I only give 2-body results. 3-body forces later...

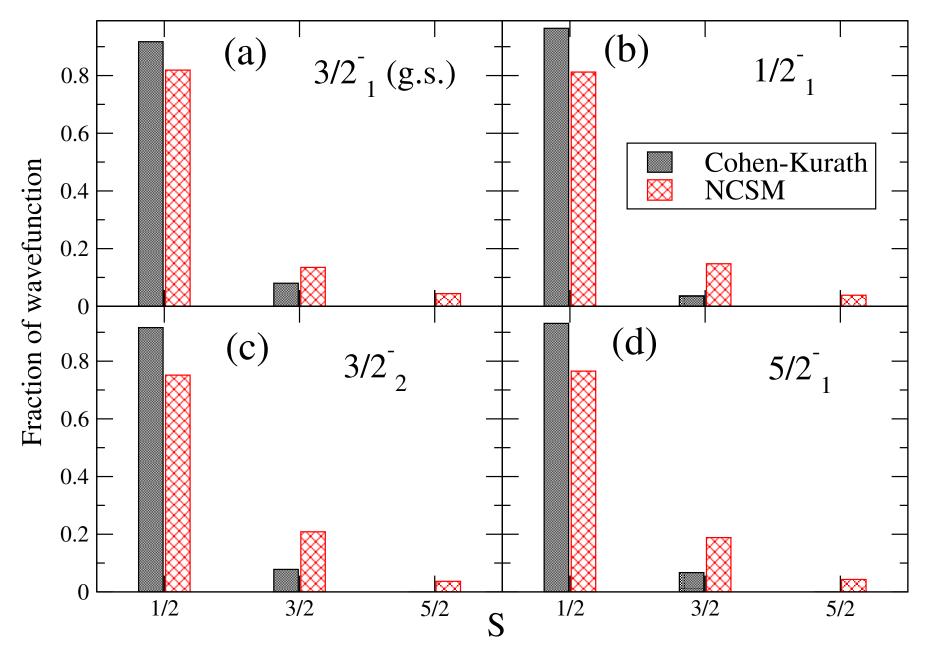
Phenomenological Cohen-Kurath *m*-scheme dimension: 62

 $^{11}\mathbf{B}$ 

NCSM: N3LO chiral 2-body force SRG evolved to  $\lambda = 2.0 \text{ fm}^{-1}$ ,  $N_{\text{max}} = 6$ ,  $\hbar \omega = 22 \text{ MeV}$  *m*-scheme dimension: 20 million



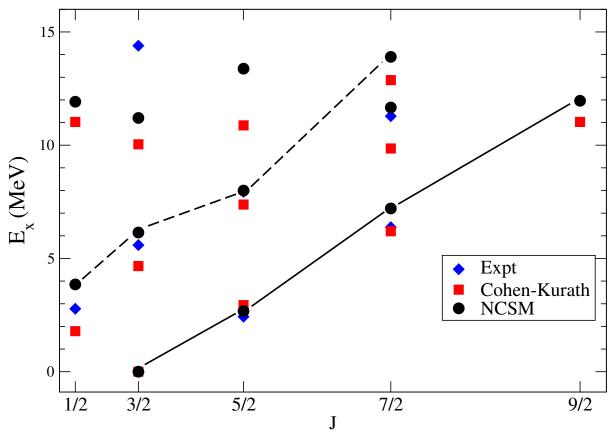




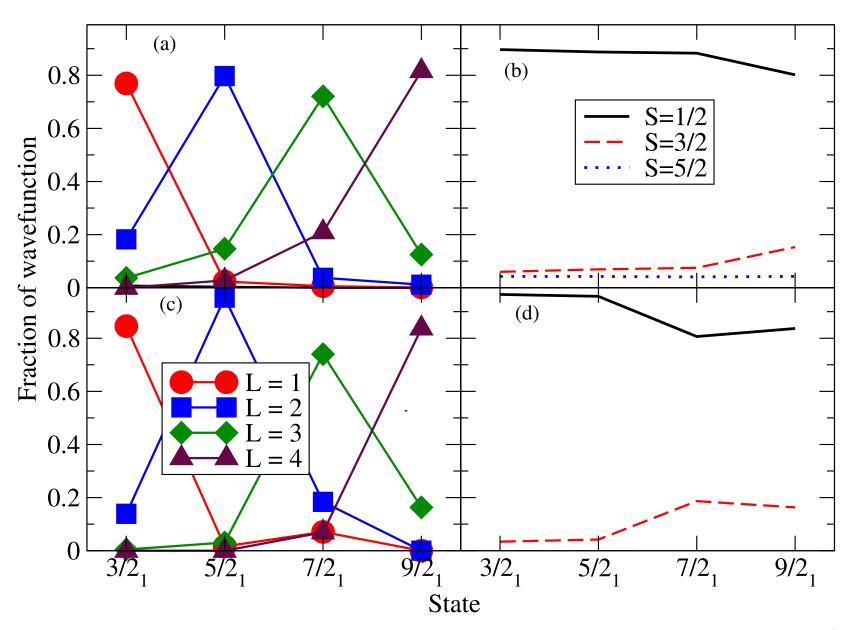
Phenomenological Cohen-Kurath m-scheme dimension: 62

<sup>9</sup>**Be** 

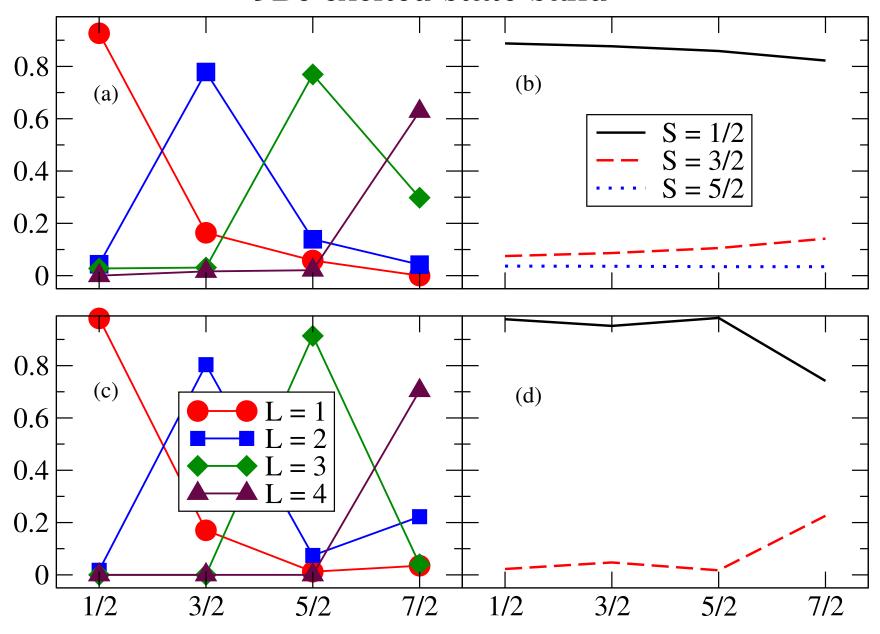
NCSM: N3LO chiral 2-body force SRG evolved to  $\lambda = 2.0 \text{ fm}^{-1}$ ,  $N_{\text{max}} = 6$ ,  $\hbar \omega = 22 \text{ MeV}$  m-scheme dimension: 5.2 million



#### 9Be ground state band



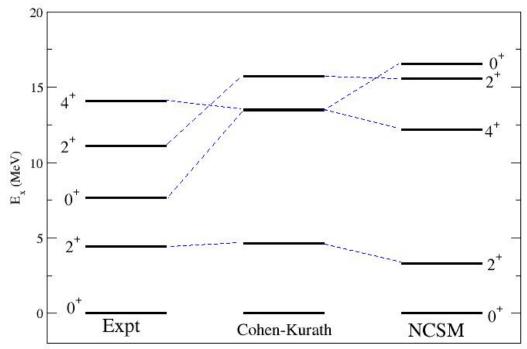
#### 9Be excited state band

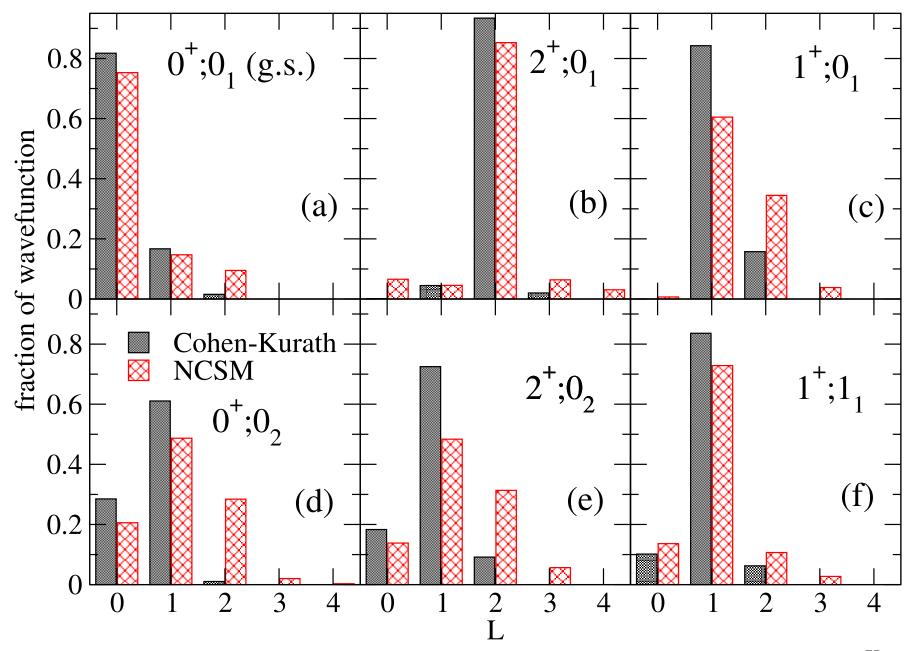


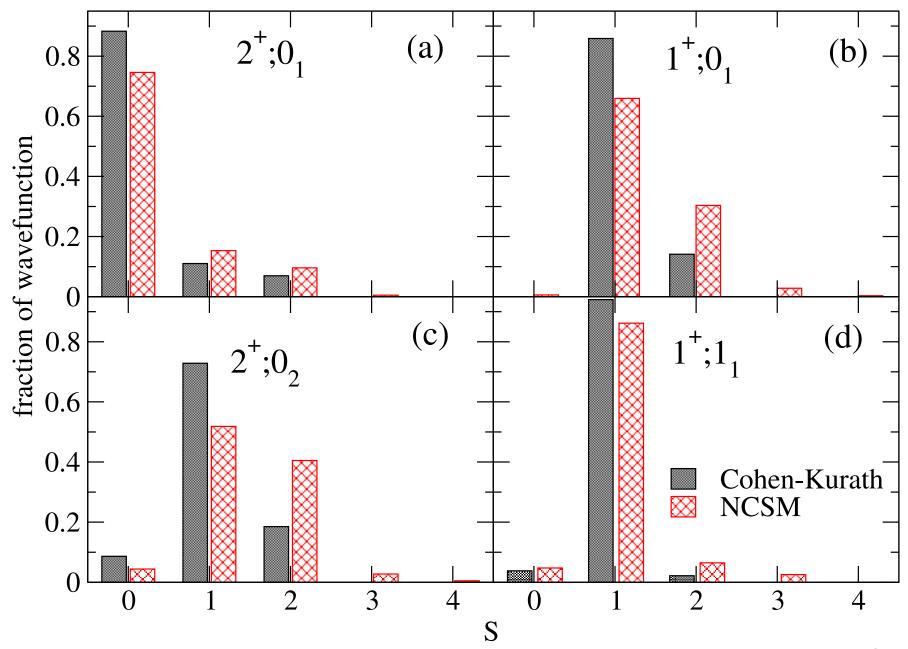
Phenomenological Cohen-Kurath force (1965) in 0p shell m-scheme dimension: 51

12**C** 

NCSM: N3LO chiral 2-body force SRG evolved\* to  $\lambda = 2.0$  fm<sup>-1</sup>,  $N_{max} = 6$ ,  $\hbar \omega = 22$  MeV *m*-scheme dimension: 35 million







#### Summary and looking forward

We live in a dynamic universe.... can't understand it without understanding transitions!

- -- We (and others) can now compute *ab initio* giant resonances in agreement with expt
- -- Some evidence for Brink hypothesis for GDRs, not so for other transitions
- -- Gamow-Teller transitions are "simple" yet behavior is not trivial (i.e., some transitions converge quickly with  $N_{\text{max}}$ , others not)
- -- Some simple pictures (L-S coupling) work across vast differences in models

#### Summary and looking forward

But getting

*calculations* = experiment

is not enough!

Can we understand systematic behavior? for example, systematics of GDRs,
Brink hypothesis

#### Some tools:

spectral distribution theory (moment methods) → Brink hypothesis → sum rules

decomposition into irreps (e.g., L-S, SU(4) irreps for Gamow-Teller)

#### "More work to be done!"